

Sparse Markov Models for High-Dimensional Inference

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Joint work with



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$a \in A$ and $x_{-k:-1} \in A^{\{-k, \dots, -1\}}$ such that $\mathbb{P}(X_{t-k:t-1} = x_{-k:t-1}) > 0$.

Denote $p(a|x_{-d:-1}) = \mathbb{P}(X_0 = a | X_{-d:-1} = x_{-d:-1})$ (**transition probabilities**).

Classical statistical questions: given a sample $X_{1:n}$ of a Markov chain,

- ▶ How to estimate the order d ?
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Typically, in the high-dimensional setting $Dim_{MC}(d_n) \gg n$. Need to seek for low dimensional (sparse) Markov chains!

Two examples of sparse Markov chains

Variable length Markov chains (VLMC) are Markov chains of order d such that

$$p(a|x_{-d:-1}) = p(a|x_{-\ell:-1}) \text{ for some } \ell = \ell(x_{-d:-1}).$$

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In this case, it follows that we need $1 \leq ne^{-cd}$ implying that $d \leq C \log n$ with $C = 1/c$.

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Why $d_n = \beta n$ is important? Many natural phenomena have very long memory!

In this talk: focus on another class of sparse Markov chains, called Mixture Transition Distribution (MTD) models.

MTD models have been introduced by A. Raftery ('85). For applications see A. Berchtold & Raftery ('02).

MTD models

Markov chains of order d such that

$$p(a|x_{-d:-1}) = \lambda_0 p_0(a) + \sum_{j=-d}^{-1} \lambda_j p_j(a|x_j),$$

where:

- ▶ $p_0(\cdot), p_j(\cdot, b), j \in \{-d, \dots, -1\}, b \in A$ are probability measures on A .
- ▶ $\lambda_0, \lambda_1, \dots, \lambda_{-d} \in [0, 1]$ such that $\sum_{j=-d}^0 \lambda_j = 1$.

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Note that $p(a|x_{-d:-1}) = p(a|x_\Lambda)$ and $Dim_{MTD}(d) = |\Lambda||A|(|A| - 1) + (|\Lambda| - 1)$.

Goal of this talk:

- ▶ to present an efficient estimator of the set of relevant lags Λ , based on a sample $X_{1:n}$ of a MTD model with order d .
- ▶ to provide some theoretical guarantees in the high-dimensional regime $\Lambda = \Lambda_n$ and $d = d_n = \beta n$ for some $\beta \in (0, 1)$.

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For a sample $X_{1:n}$, integer $m < n$, $S \subseteq \{-d, \dots, -1\}$, $x_S \in A^S$ and $a \in A$, let

$$\hat{p}_{m,n}(a|x_S) = \begin{cases} \frac{N_{m,n}(x_S, a)}{\bar{N}_{m,n}(x_S)}, & \text{if } \bar{N}_{m,n}(x_S) > 0, \\ 1/|A|, & \text{otherwise} \end{cases},$$

In the definition of $\hat{p}_{m,n}(a|x_S)$ the countings are over $X_{m+1:n}$.

FSC estimator

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Step 1 (FS). From $X_{1:m}$, build a random set \hat{S}_m such that $\Lambda \subseteq \hat{S}_m$ with high probability.

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Step 2 (CUT). For each $j \in \hat{S}_m$, remove j from \hat{S}_m only if

$$d_{TV}(\hat{p}_{m,n}(\cdot|x_{\hat{S}_m}), \hat{p}_{m,n}(\cdot|y_{\hat{S}_m})) < t_{m,n}(x_{\hat{S}_m}, y_{\hat{S}_m}),$$

for all $x_{\hat{S}_m}, y_{\hat{S}_m} \in A^{\hat{S}_m}$ s.t. $x_k = y_k$ for all $k \in \hat{S}_m \setminus \{j\}$.

Choice of the random threshold

For $S \subseteq \{-d, \dots, -1\}$, $x_S \in A^S$, we take $t_{m,n}(x_S, y_S) = s_{m,n}(x_S) + s_{m,n}(y_S)$, where

$$s_{m,n}(x_S) = \sqrt{\frac{\alpha(1+\varepsilon)}{2\bar{N}_{m,n}(x_S)}} \sum_{a \in A} \sqrt{V_{m,n}(a, x_S)} + \frac{\alpha|A|}{6\bar{N}_{m,n}(x_S)},$$

with $\alpha, \varepsilon > 0$, $\mu \in (0, 3)$ s.t. $\mu > \psi(\mu) = e^\mu - 1 - \mu$ and

$$V_{m,n}(a, x_S) = \frac{\mu}{\mu - \psi(\mu)} \hat{p}_{m,n}(a|x_S) + \frac{\alpha}{\bar{N}_{m,n}(x_S)(\mu - \psi(\mu))}.$$

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The choice of $s_{m,n}(x_S)$ is based on a Martingale concentration inequality.

How do we build \hat{S}_m ?

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From now on, we focus on the case $A = \{0, 1\}$.

Assumption 1. $\mathbb{P}(X_S = x_S) > 0$ for all $S \subseteq \{-d, \dots, -1\}$ and $x_S \in \{0, 1\}^S$.

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Proposition 1. Under Assumption 1 there exists $\kappa > 0$ such that the following property holds: for all $S \subseteq \{-d, \dots, -1\}$ with $\Lambda \not\subseteq S$, it holds that

$$\max_{j \in S^c} \bar{\nu}_{j,S} \geq \max_{j \in \Lambda \setminus S} \bar{\nu}_{j,S} \geq \kappa$$

Denote $\hat{\nu}_{m,j,S}$ the empirical estimate of $\bar{\nu}_{j,S}$ computed from $X_{1:m}$.

To build \hat{S}_m , we do as follows. Fix $0 \leq \ell \leq d$.

1. Set $\hat{S}_m = \emptyset$.
2. While $|\hat{S}_m| < \ell$, compute $j \in \arg \max_{k \in \hat{S}_m^c} \hat{\nu}_{m,k,\hat{S}_m}$ and include j in \hat{S}_m .

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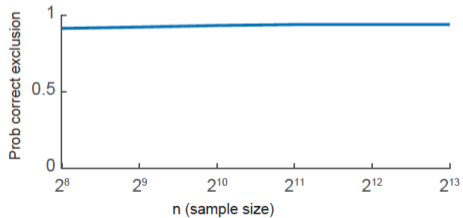
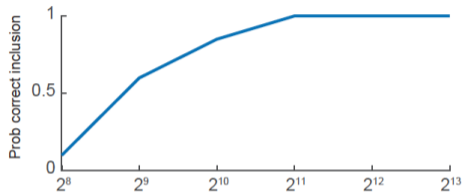
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Theorem 1. (Consistency) Take $m = n/2$ and assume $d = \beta m$ for some $\beta \in (0, 1)$. Suppose Assumption 1 holds and let $\kappa > 0$ given by Proposition 1. Let $\hat{\Lambda}_n$ be the FSC estimator computed with $\ell = 2\kappa^{-2}$ and $\alpha = (1 + \eta) \log(n)$ for some $\eta > 0$. Under some other mild assumptions and if $\ell \leq (1 - \gamma)/2 \log_2(n)$ for some $\gamma \in (0, 1)$, then there exists a constant $C > 0$ such that $\mathbb{P}(\hat{\Lambda}_n \neq \Lambda) \rightarrow 0$ as $n \rightarrow \infty$, as long as

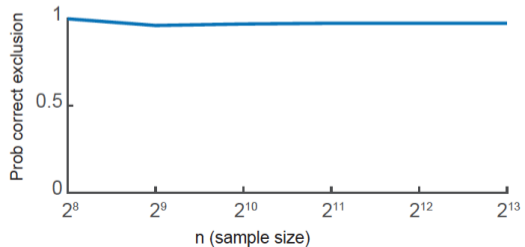
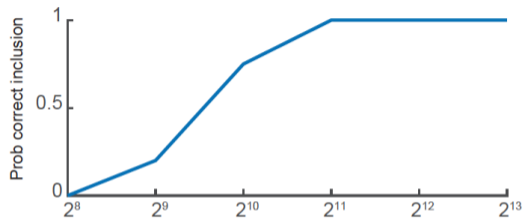
$$\min_{j \in \Lambda} \delta_j^2 \geq C \frac{\log(n)}{n^{(1+\gamma)/2}}.$$

Simulations: FSC estimator

$l = 5, d = 50, \text{lags} = \{11, 21\}, \text{with cut}$

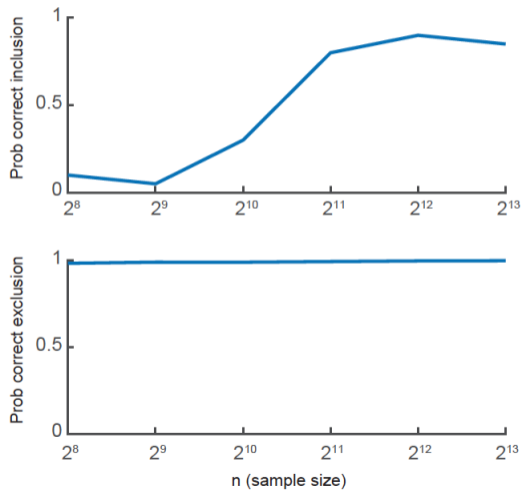


$l = 5, d = 120, \text{lags} = \{11, 100\}, \text{with cut}$



Simulations: FSC estimator

$l = 5, d = n/4, \text{lags} = \{11, 21\}, \text{with cut}$



Simulations: transition probability estimation

MTD model used: $p(a|x_{-d:-1}) = \lambda_0 p_0(a|x_0) + \lambda_i p_i(a|x_i) + \lambda_j p_j(a|x_j)$ where $\lambda_0 = 0.2$, $\lambda_i = \lambda_j = 0.4$, $p_i(0|0) = p_i(1|1) = p_j(0|0) = p_j(1|1) = 0.7$.

For each choice of i, j, d , and n we simulated 100 realizations. For each realization, we estimated the transition probability $p(0|0^d)$.

Model parameter			Method	Sample size (n)					
i	j	d		256	512	1024	2048	4096	8192
1	5	5	FSC(2)	0.0774	0.0682	0.0506	0.0286	0.0174	0.0133
1	5	5	FSC(5)	0.0745	0.0835	0.0602	0.0426	0.0222	0.0129
1	5	5	PCP	0.0965	0.0786	0.0577	0.0432	0.0242	0.0131
1	5	5	Naive	0.1518	0.0933	0.0624	0.0455	0.0340	0.0252
1	5	10	FSC(5)	0.0836	0.0842	0.0659	0.0425	0.0228	0.0141
1	10	15	FSC(5)	0.0864	0.0781	0.0641	0.0438	0.0249	0.0151
1	15	20	FSC(5)	0.0682	0.0802	0.0778	0.0534	0.0285	0.0138
11	100	120	FSC(5)	-	-	0.0838	0.0647	0.0312	0.0169
1	10	n/8	FSC(5)	0.0563	0.0543	0.0780	0.0698	0.0504	0.0105

Further theoretical guarantees of FSC estimator

Theorem 2. Take $m = n/2$ and assume $d = \beta m$ for $\beta \in (0, 1)$. Suppose $|\Lambda| \leq L$ with L known and the MTD model satisfies some weak dependence conditions. Let $\hat{\Lambda}_n$ be the FSC estimator constructed with parameters $\ell = L$ and $\alpha = (1 + \eta) \log(n)$ for $\eta > 0$. Under some other mild assumptions, there exists a positive constant $C > 0$ such that

$$\mathbb{P}(\hat{\Lambda}_n \neq \Lambda) \rightarrow 0 \text{ as } n \rightarrow \infty,$$

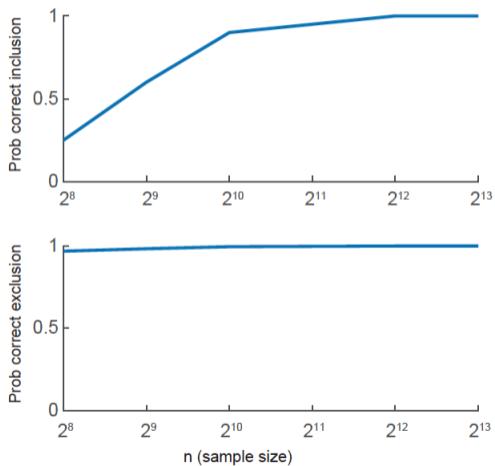
as long as

$$\min_{j \in \Lambda} \delta_j^2 \geq C \frac{\log(n)}{n}.$$

If $|\Lambda| = L$ and the MTD satisfies the weak dependence conditions, then we estimate Λ by $\hat{\Sigma}_m$. In this case, we neither need the CUT step nor to split the data into two pieces!

Simulations: FSC without CUT

$l = 2, d = 50, \text{lags} = \{11, 21\}, \text{without cut}$



Final comments

If in Theorem 1 we suppose also that the Inward weak condition holds, then

$$\kappa = \frac{\Gamma_1 p_{\min}^2 \min_{j \in \Lambda} \delta_j}{2\sqrt{|\Lambda|}}.$$

The lag selection is possible (in the minimax sense) only if

$$\min_{j \in \Lambda} \delta_j^2 \geq C \frac{\log(n)}{n}.$$

What about multivariate MTD models?