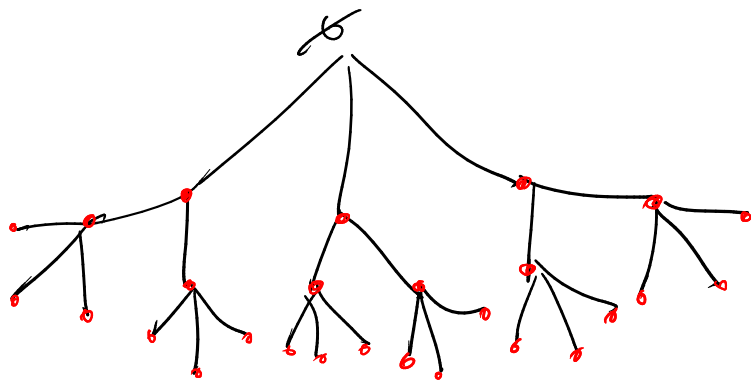


Bondanda & Dean trap model on Parisi's tree



(mean field)

(phenomenological model for a spin glass dynamics)

Site in generation $i-1 \rightarrow M_i$ descendants ($i=1, \dots, k$)

Each node $\underline{x}_i = x_1 - x_i \rightarrow$ Poisson clock ($\lambda_{\underline{x}_i}^i = (\delta_{\underline{x}_i}^i)^{-1}$)

$\delta^i \equiv \{ \delta_{\underline{x}_i}^i \}_{\underline{x}_i}$ iid attracted to $\alpha_i \stackrel{(0,1)}{\leftarrow}$ stable law

$\delta^1, \dots, \delta^k$ independent ... random env.

Dynamics (on leaves of tree)

When at \underline{x}_k , an ancestor \underline{x}_{i-1} of \underline{x}_k is chosen as the mother of the site (\underline{x}_i) whose clock rings 1st, and the dynamics jumps from \underline{x}_k to a descendant \underline{x}'_k of \underline{x}_{i-1} in the k -th gen. chosen unif'ly at random.

Alternatively

$$\lambda_{x_1}^1 + \lambda_{x_2}^2 + \dots + \lambda_{x_k}^k$$

When at x_k , wait for $\exp(\lambda_{x_k}^k)$; then choose ascendant x_i w.p. $\lambda_{x_i}^i / \lambda_{x_k}^k$; then jump to descendant of x_{i-1} chosen uniformly at random in k -th gen.

(Comparison to) Sasaki-Nemoto (GREM-like) trap model

When at x_k , wait for $\exp(\lambda_{x_k}^k)$; then choose ascendant x_{i-1} by flipping coins successively on $x_{k-1}, \dots, x_1, \emptyset$, w.p.

$P_{x_{k-1}}^{k-1}, \dots, P_{x_1}^1, P_{\emptyset}^0 = 0$ of heads, resp., until getting tails,

$$P_{x_i}^i = \frac{1}{1 + (\lambda_{x_i}^i)^{-1}} ;$$

(x_{i-1} is where succession stops) then choose descendant of x_{i-1} in k -th gen, as before.

Medidas de equilibrio ($k=2$, pro simpliciter)

$$g(x_2) = \frac{\beta_{x_1}'}{\sum_{y_1} \beta_{y_1}'} \cdot \frac{\beta_{x_2}^2}{\beta_{x_1} + \beta_{x_2}^2} \quad (\text{BDM})$$

$$g'(x_2) = \frac{(1 + \beta_{x_1}') \beta_{x_2}^2}{\sum_{y_2} (1 + \beta_{y_1}') \beta_{y_2}^2} \quad (\text{SNTM})$$

Limite de scala (equilibrio)

Rescalando apropiada/le $\mu_i \rightarrow \infty$ $\forall i$:

$$f(\underline{x}_2) = \frac{\delta_{x_1}^1}{\sum_{y_1} \delta_{y_1}^1} \frac{\frac{\delta_{x_1 x_2}^2}{\delta_{x_1}^1 + \delta_{x_1 x_2}^2}}{\sum_{y_2} \frac{\delta_{x_1 y_2}^2}{\delta_{x_1}^1 + \delta_{x_1 y_2}^2}} \quad (\text{BDTM})$$

$$f'(\underline{x}_2) = \frac{\delta_{x_1}^1 \delta_{x_1 x_2}^2}{\sum_{y_1 y_2} \delta_{y_1}^1 \delta_{x_1 y_2}^2} \quad (\text{SNTM})$$

\rightarrow coincides with ∞ -vst.
GREN Gibbs measure

where $\left\{ \delta_x^1 \right\}_{x \in [0,1]}$ increments of α_1 - stable subordinator

$\forall x \left\{ \delta_{xy}^2 \right\}_{y \in [0,1]}$ ----- α_2 -----

\rightarrow all subordinators ind. from each other

For SNTM: $\alpha_1 < \alpha_2$

\downarrow
no such need in BDTM

\downarrow
but the authors do not seem to have realized it!

* can relax on the μ_i 's appropriately

Want to take the scaling limit of dynamics

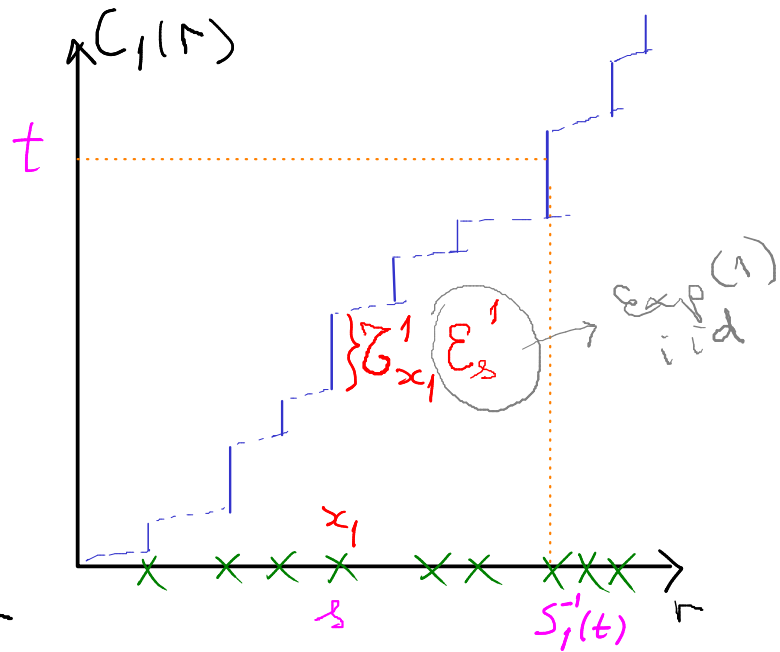
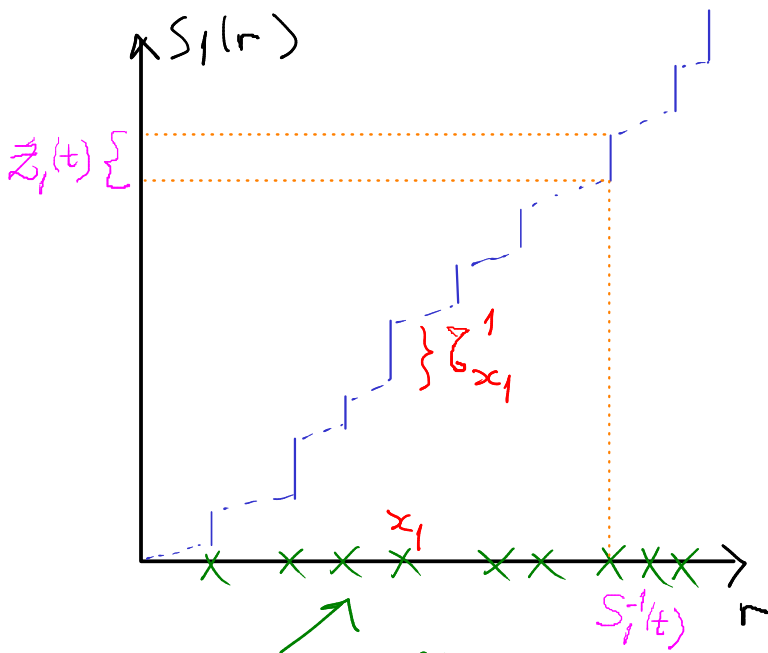
(3 regimes: near equilibrium; 2 reg's far from eq.) → aging

Convenient representation of dynamics:

instead of recording the positions (at given times):
record the values of respective $\delta_{x_i}^i$'s;

think of following construction:

1st level ($k=1$)



some (labeled) marks of superposition of M_1 PPP(1)

→ jumps of $S_1 = \int_1$

$$S_1(r) = \sum_{\substack{s \in \mathcal{I}_1 \\ s \leq r}} \underbrace{\delta_{x_s}^1}_{\delta_{x_s}^1}$$

time br
clock process

$\delta_{x_s}^1 \rightarrow$ no jumps be s

clock process

$$C_1(r) = \int_{\substack{s \in \mathcal{I}_1 \\ s \leq r}} \delta_{x_s}^1 \epsilon_s^1$$

$$= \int_0^r \epsilon_s^1 dS_1(s)$$

Limite de scala de $S_1 \Rightarrow$ Limite de scala de C_1

\Rightarrow Limite de scala de Z_1

$$S_1(r) = \sum_{x_1=1}^{M_1=n} \sum_{x_2}^1 N_{x_1}^1(r)$$

PP(1) iid

3 regims de scala

invar. of α_1 -stable subordinator

$$1) S_1^{(n)}(r) = \frac{1}{n^{1/\alpha_1}} S_1(r) \xrightarrow[n \rightarrow \infty]{d} \int_{x \in [0,1]} \sum_{x_1}^1 N_{x_1}^1(r)$$

(ergodic regime)

$$Z_1^{(n)}(t) = \frac{1}{n^{1/\alpha_1}} Z_1(n^{1/\alpha_1} t) \xrightarrow[n \rightarrow \infty]{d} \tilde{Z}_1(t) \dots \kappa\text{-process}$$

\rightarrow ergodic
 \Rightarrow no aging

$$2) \hat{S}_1^{(n)}(r) = \frac{1}{n^\beta} S_1(a_1^{(n)} r) ; 0 < \beta < 1/\alpha_1, a_1^{(n)} = n^{\alpha_1 \beta - 1}$$

(psly. sub ergodic regime)

$$\xrightarrow[n \rightarrow \infty]{\mathcal{D}_0} \hat{S}(r) \dots \alpha_1\text{-stable subordinator}$$

$$\hat{Z}_1^{(n)}(t) = \frac{1}{n^\beta} Z_1(n^\beta t) \xrightarrow[n \rightarrow \infty]{d} \hat{Z}_1(t) \text{ for a.e. } (\mathcal{D}_1)$$

\dots visits jumps of \hat{S} in order
 spends $\text{Exp}(\gamma_2^1)$ in s
 \rightarrow aging

Asing of \hat{z}_1

$$\int_0^{\cdot} \varepsilon'_s d\hat{S}_1^{(n)}(s)$$

$$P(\text{no jump of } \hat{z}_1^{(n)} \text{ during } (t_w, t_w+t))$$

α_1 -stable subordinator

$$= P((t_w, t_w+t) \cap \text{Range of } \hat{C}_1^{(n)} = \emptyset)$$

$$\int_0^{\cdot} \varepsilon'_s d\hat{S}_1(s)$$

gc
 $n \rightarrow \infty$
 $\rightarrow P(\text{---} \hat{C}_1 \text{---})$

$$= P(\text{no jump of } \hat{z}_1 \text{ during } (t_w, t_w+t)) = f_n \text{ of } t/t_w$$

arcsine law

$$\text{Beta}(1-\alpha_1, \alpha_1) \sim \leftarrow = P(U_1 > \frac{t}{t+t_w})$$

$$3) \sum_1^{(n)}(r) = S_1^{(n)}\left(\frac{r}{n}\right) \xrightarrow[n \rightarrow \infty]{d} \int_{x_1=1}^{N_r^1} \sigma'_{x_1} \text{ for a.e. } (\sigma'_{x_1})$$

(order 1 subordinator regime)

$$\hat{z}_1^{(n)}(t) \xrightarrow[n \rightarrow \infty]{d} \hat{z}_1(t) \text{ for a.e. } (\sigma'_{x_1})$$

$\hat{z}_1(r)$

$$\bar{S}_1^{(m)}(r) = \frac{1}{m^{1/\alpha_1}} S_1^V(mr) \xrightarrow[m \rightarrow \infty]{d} \hat{S}_1(r) \dots \alpha_1\text{-stable subordinator}$$

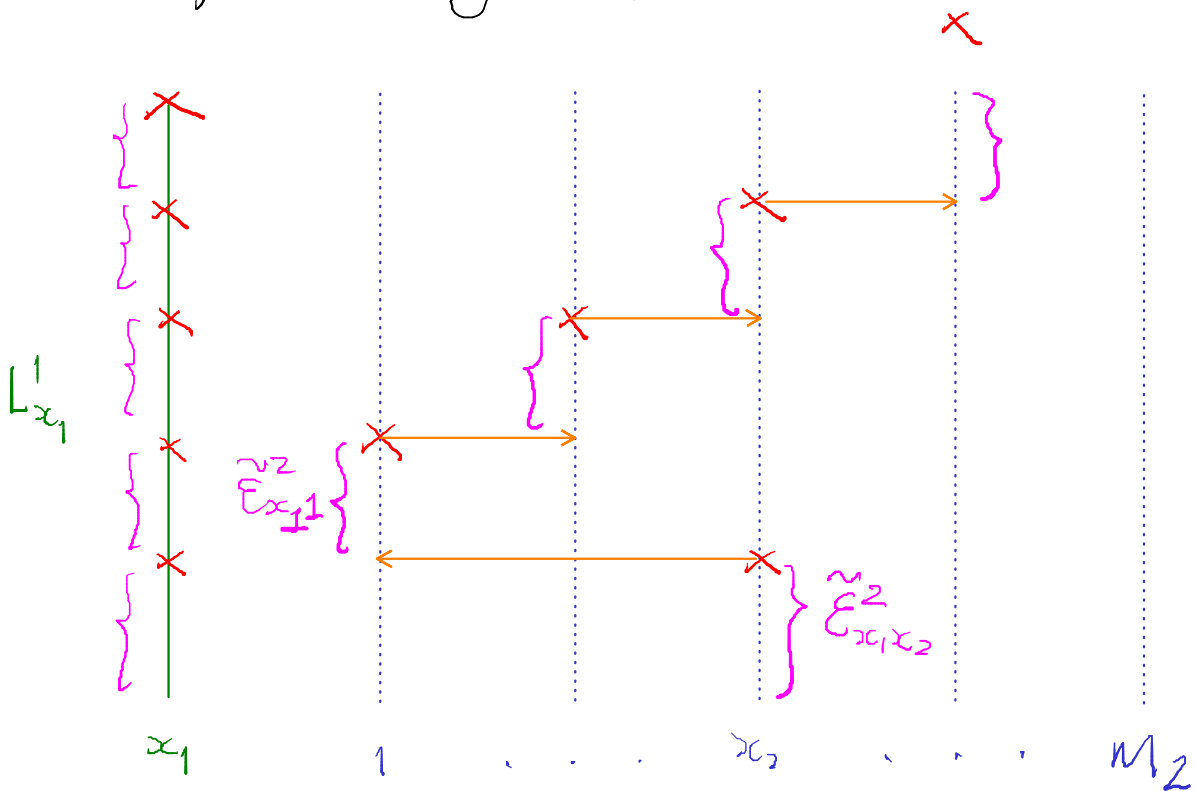
$$\bar{z}_1^{(m)}(t) = \frac{1}{m^{1/\alpha_1}} z_1^V(mt) \xrightarrow[m \rightarrow \infty]{d} \hat{z}_1(t)$$

Asing: $\lim_{m \rightarrow \infty} \lim_{n \rightarrow \infty} P(\text{no jump of } z_1 \text{ during } m^{1/\alpha_1}(t_w, t_w+t)) = \text{arcsine law for a.e. } (\sigma'_{x_1})$

2nd level

Enough to understand dynamics on 2nd level while resting at any given x_1 on the 1st level (during a time interval of length $L_{x_1}^1 = \exp(\lambda_{x_1}^1)$).

Key ingredient: durations of visits to level 2 sites before reaching $L_{x_1}^1$

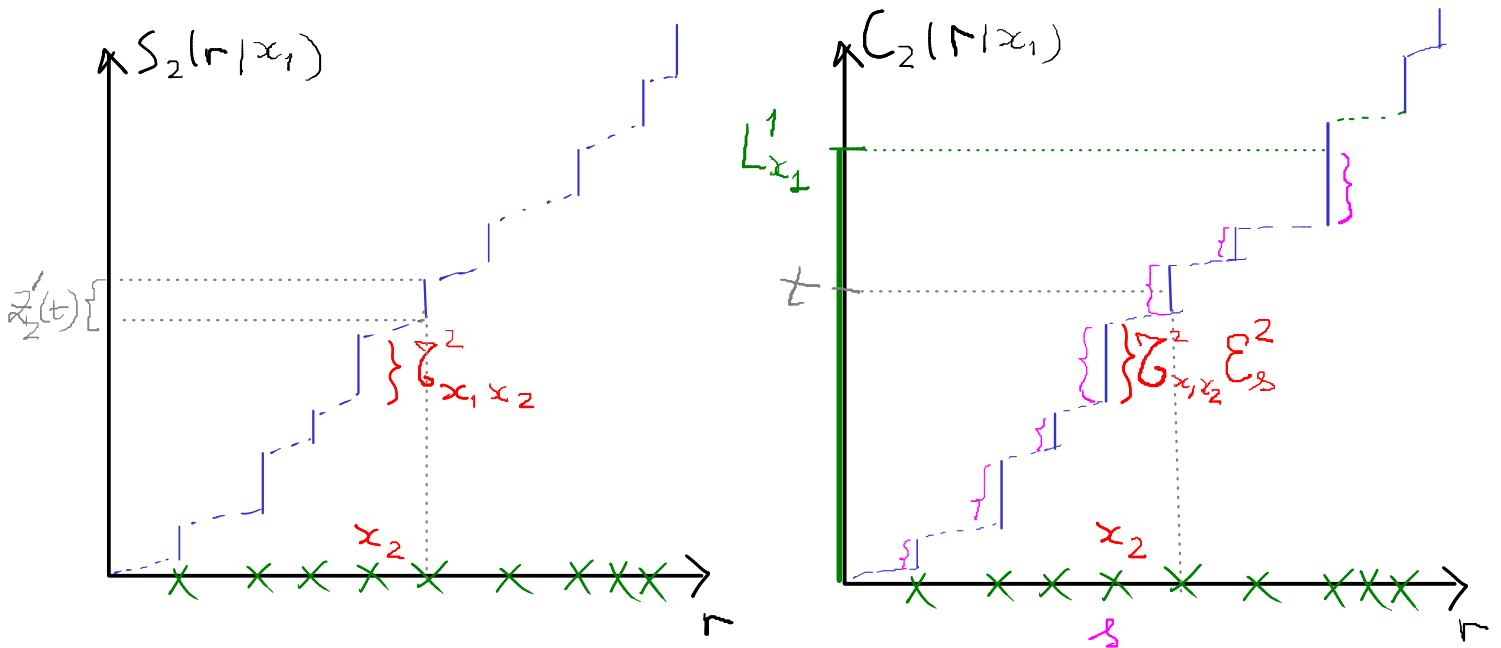


Successive E_{x_1,x_2}^2 , $E_{x_1,x_2'}^2$, ... up to last one (before jumping on 1st level):

incl. exp. r.v.'s w. rates $\lambda_{x_1}^1 + \lambda_{x_1,x_2}^2$, $\lambda_{x_1}^1 + \lambda_{x_1,x_2'}^2$, ..., resp.

2nd level dynamics during a sojourn of 1st level on x_1 :

return of 1st level dynamics:



A more convenient* representation of 2nd level states (instead of $z_2(t) = \text{current value of } E_{x_1, x_2}^2$):

$$z_2(t) = \text{current value of } \frac{1}{\lambda_{x_1}^1 + \lambda_{x_1, x_2}^2}$$

... expected jump time when at x_1, x_2 at time t

* for technical reasons, but it is more natural in the aging investigation context

Scaling limit of 2 level dynamics

(Assume appropriate rel. relation: $M_1^{1/\alpha_1} = M_2^{1/\alpha_2}$;
so that (rescaled) S_1 & $S_2(x_1)$, $x_1 = 1, 2, \dots$,
converge to the same kind of limit in
regimes 1 & 2 above; regime 3 does not require that.

∞ volume construction of 2nd level
dynamics (within sojourns of 1st
level dyn.) as above.

Scaling limit results for dynamics

follow in 3 regimes

- ergodic - no aging
- poly suberg. } aging
- $O(1)$ " " }

OC1) aging result

$$\lim_{m \rightarrow \infty} \lim_{M_1, M_2 \rightarrow \infty} P(\text{no jump of } (Z_1, Z_2) \text{ in } m^{1/\alpha_i} [t_w, t_w + t])$$

limit of process
↙

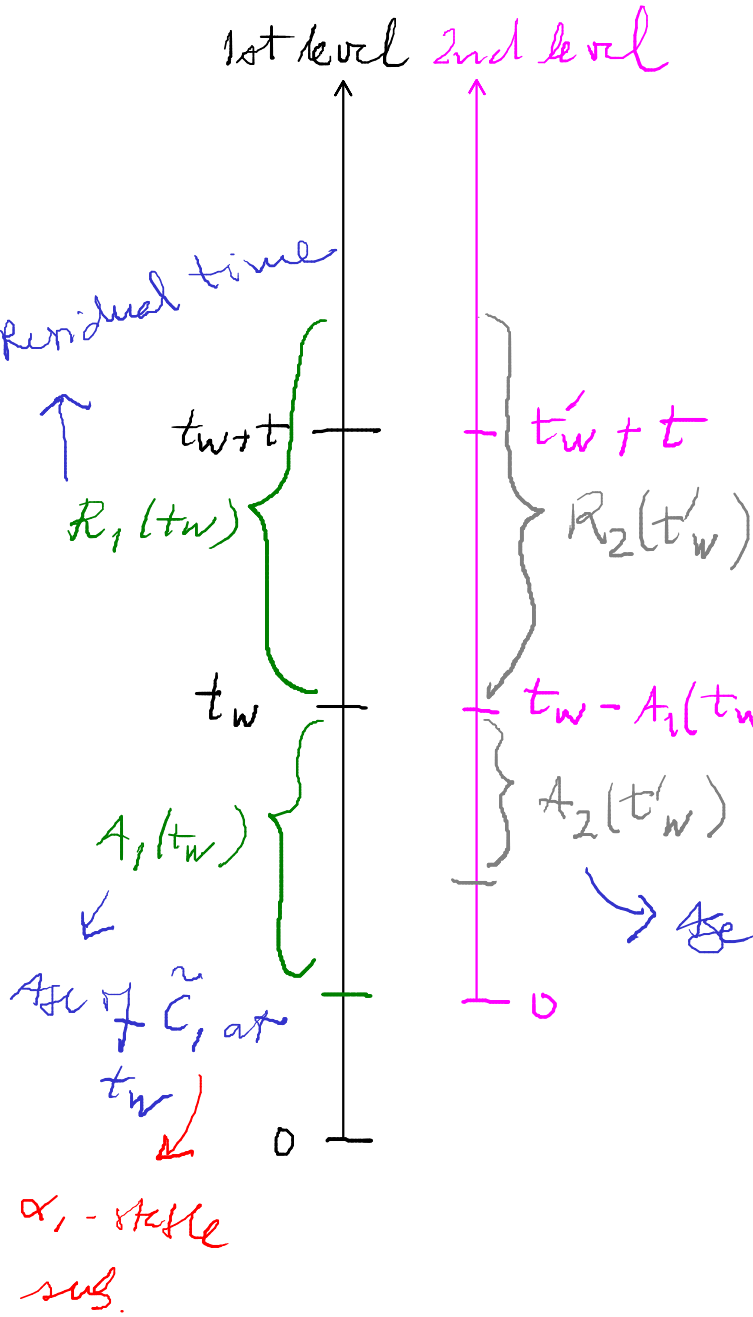
$$= P(\text{no jump of } (\tilde{Z}_1, \tilde{Z}_2) \text{ in } [t_w, t_w + t])$$

*

$$= P(U_1 U_2 > t / (t + t_w)) \text{ for a.e. } (\bar{\alpha}_i)$$

$U_i \sim \text{Beta}(1 - \alpha_i, \alpha_i)$ i.i.d.

Argument for $*$:



r.h.s. of $*$ =

$$P(R_1(t_w) > t_w + t, R_2(t'_w) > t'_w + t)$$

r.h.s. of $*$ follows readily from scaling relations of stable subord. (of index < 1), other known results for these processes & indep.